

Adjust motor drive torque. Max. 245. Please kindly note that the higher the torque is, the bigger the current is, and bigger current will shorten servo life and cause vibration. Adjusting 100% PWM value together with this value allows you to adjust servo output torque as well.

Boost : 启动脉冲宽度 设置电机从静止开始启动的脉冲宽度, 调整这项可以使舵机转动更平滑, 调试数值太小会造成抖动。

Boost : The Pulse-Width to start the motor. It makes the servo more smooth by adjusting the values. It will cause the vibration if the value is too small.

Pulse Lower : 信号识别范围 设置(最小值)。推荐值 900 μ s, 调整这项可以改变舵机的行程角度, 最小为 600 μ s

Pulse Lower Recommended value: 900 μ s, Min. 600 μ s. Servo travel range angle Pulse Lower : can be adjusted by changing this value.

Pulse High : 信号识别范围 设置(最大值)。推荐值 2100 μ s., 最大为 2400 μ s

Pulse High Recommended value: 2100 μ s, Max. 2400 μ s

Left Range : 中点到最大脉冲的角度 设置(最大值)。通常设置为 0, 当设置为负数角度变小, 正数时角度变大, 可以改变同一个脉宽下舵机所对应的角度。

Left Range : To set the Max.value. The value is usually set to be 0. The servo travel degree will decrease with the value of -, and increase with the value of +. This feature allows you to change the servo degree in corresponding to the same pulse width.

Right Range : 中点到最大脉冲的角度设置(最大值)。通常设置为 0, 当设置为负数角度变小, 正数时角度变大, 可以变更同一个脉宽下的角度。

Right Range : To set the Max.value. The value is usually set to be 0. The servo travel degree will decrease with the value of -, and increase with the value of +. This feature allows you to change the servo degree in corresponding to the same pulse width.

Neutral : 舵机中点调制 调整舵机中点位置, 通常设置为0, 此处不要调整。

Neutral : This feature allows you to set your Center point. The value is usually set to be 0. Please do not change this value.

Drive Frequency : 电机驱动频率 推荐值 330、19531, 别的使用会造成舵机异常。可以减少舵机吱吱响声。

Drive Frequency : It allows you to lower the squeaky noise of the servo. Recommended value: 330, 19531. Other value may cause servo malfunction. 功能选择区 :

Internal Osc : 内部震荡使能控制位, 当选择该位时无需外接震荡器舵机即可工作, 此处不要做调整, 否则舵机会不正产工作。

Internal Osc : When this feature is chosen, external oscillator is unnecessary. Please don't change this mode or else it will cause servo malfunction.

Inverter : 舵机反向控制位, 选择该位后舵机将改变转向。

Inverter : To change the direction of rotation of the servo for a given stick movement direction. 100% PWM :

100% PWM 使能控制位, 可以调节舵机输出扭力。

Adjust servo torque.

Narrow Band : 窄频模式, 选择该位后 IC 将被配置为窄频模式, 信号识别范围会随着该位的使能发生变化, 此处调整需注意, 如果你陀螺仪不支持窄频模式, 请不要修改。

When Narrow Band is chosen, IC is set to be Narrow Band mode, the range of signal recognition will be changed.

Please do not choose this feature if the gyro doesn't support Narrow Band mode.